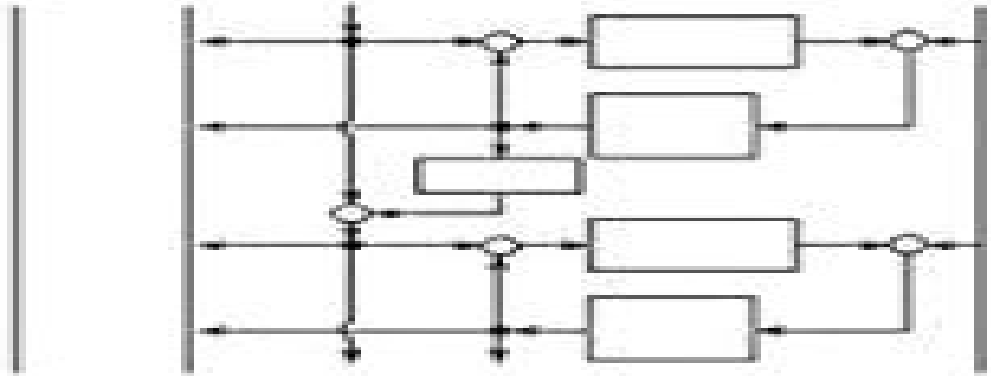
Lecture Notes in Control and Information Sciences 248

Yangquan Chen and Changyun Wen

Iterative Learning Control

Convergence, Robustness and Applications



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Iterative Learning Control Convergence Robustneb And Applications

Wenjun Xiong,Zijian Luo,Daniel W. C. Ho

Iterative Learning Control Convergence Robustneb And Applications:

Iterative Learning Control Yangquan Chen,Changyun Wen,2014-03-12 This book provides readers with a comprehensive coverage of iterative learning control The book can be used as a text or reference for a course at graduate level and is also suitable for self study and for industry oriented courses of continuing education Ranging from aerodynamic curve identification robotics to functional neuromuscular stimulation Iterative Learning Control ILC started in the early 80s is found to have wide applications in practice Generally a system under control may have uncertainties in its dynamic model and its environment One attractive point in ILC lies in the utilisation of the system repetitiveness to reduce such uncertainties and in turn to improve the control performance by operating the system repeatedly This monograph emphasises both theoretical and practical aspects of ILC It provides some recent developments in ILC convergence and robustness analysis The book also considers issues in ILC design Several practical applications are presented to illustrate the effectiveness of ILC The applied examples provided in this monograph are particularly beneficial to readers who wish to capitalise the system repetitiveness to improve system control performance *Iterative Learning Control* Yangquan Chen,Changyun Wen,2007-10-03 This book provides readers with a comprehensive coverage of iterative learning control The book can be used as a text or reference for a course at graduate level and is also suitable for self study and for industry oriented courses of continuing education Ranging from aerodynamic curve identification robotics to functional neuromuscular stimulation Iterative Learning Control ILC started in the early 80s is found to have wide applications in practice Generally a system under control may have uncertainties in its dynamic model and its environment One attractive point in ILC lies in the utilisation of the system repetitiveness to reduce such uncertainties and in turn to improve the control performance by operating the system repeatedly This monograph emphasises both theoretical and practical aspects of ILC It provides some recent developments in ILC convergence and robustness analysis The book also considers issues in ILC design Several practical applications are presented to illustrate the effectiveness of ILC The applied examples provided in this monograph are particularly beneficial to readers who wish to capitalise the system repetitiveness to improve system control performance **Iterative Learning Control** Hyo-Sung Ahn,Kevin L. Moore,YangQuan Chen,2007-06-28 This monograph studies the design of robust monotonically convergent it ative learning controllers for discrete time systems Iterative learning control ILC is well recognized as an e cient method that o ers signi cant p formance improvement for systems that operate in an iterative or repetitive fashion e g robot arms in manufacturing or batch processes in an industrial setting Though the fundamentals of ILC design have been well addressed in the literature two key problems have been the subject of continuing search activity First many ILC design strategies assume nominal knowledge of the system to be controlled Only recently has a comprehensive approach to robust ILC analysis and design been established to handle the situation where the plant model is uncertain Second it is well known that many ILC algorithms do not produce monotonic convergence though in applications

monotonic convergencecan be essential This monograph addresses these two keyproblems by providingauni ed analysisanddesignframeworkforrobust monotonically convergent ILC The particular approach used throughout is to consider ILC design in the iteration domain rather than in the time domain Using a lifting technique the two dimensionalILC system whichhas dynamics in both the time and eratiomdomains istransformedintoaone dimensionalsystem withdynamics only in the iteration domain The so called super vector framework resulting from this transformation is used to analyze both robustness and monotonic convergence for typical uncertainty models including parametric interval certainties frequency like uncertainty in the iteration domain and iterati domain stochastic uncertainty Iterative Learning Control Zeungnam Bien,Jian-Xin Xu,2012-12-06 Iterative Learning Control ILC differs from most existing control methods in the sense that it exploits every possibility to incorporate past control informa tion such as tracking errors and control input signals into the construction of the present control action There are two phases in Iterative Learning Control first the long term memory components are used to store past control infor mation then the stored control information is fused in a certain manner so as to ensure that the system meets control specifications such as convergence robustness etc It is worth pointing out that those control specifications may not be easily satisfied by other control methods as they require more prior knowledge of the process in the stage of the controller design ILC requires much less information of the system variations to yield the desired dynamic be haviors Due to its simplicity and effectiveness ILC has received considerable attention and applications in many areas for the past one and half decades Most contributions have been focused on developing new ILC algorithms with property analysis Since 1992 the research in ILC has progressed by leaps and bounds On one hand substantial work has been conducted and reported in the core area of developing and analyzing new ILC algorithms On the other hand researchers have realized that integration of ILC with other control techniques may give rise to better controllers that exhibit desired performance which is impossible by any individual approach **High-order Iterative Learning Control** Yangquan Chen,1997 **Iterative Learning Control** David H. Owens,2015-10-31 This book develops a coherent and quite general theoretical approach to algorithm design for iterative learning control based on the use of operator representations and quadratic optimization concepts including the related ideas of inverse model control and gradient based design Using detailed examples taken from linear discrete and continuous time systems the author gives the reader access to theories based on either signal or parameter optimization Although the two approaches are shown to be related in a formal mathematical sense the text presents them separately as their relevant algorithm design issues are distinct and give rise to different performance capabilities Together with algorithm design the text demonstrates the underlying robustness of the paradigm and also includes new control laws that are capable of incorporating input and output constraints enable the algorithm to reconfigure systematically in order to meet the requirements of different reference and auxiliary signals and also to support new properties such as spectral annihilation Iterative Learning Control will interest academics and graduate

students working in control who will find it a useful reference to the current status of a powerful and increasingly popular method of control The depth of background theory and links to practical systems will be of use to engineers responsible for precision repetitive processes **Iterative Learning Control with Passive Incomplete Information** Dong Shen,2018-04-16 This book presents an in depth discussion of iterative learning control ILC with passive incomplete information highlighting the incomplete input and output data resulting from practical factors such as data dropout transmission disorder communication delay etc a cutting edge topic in connection with the practical applications of ILC It describes in detail three data dropout models the random sequence model Bernoulli variable model and Markov chain model for both linear and nonlinear stochastic systems Further it proposes and analyzes two major compensation algorithms for the incomplete data namely the intermittent update algorithm and successive update algorithm Incomplete information environments include random data dropout random communication delay random iteration varying lengths and other communication constraints With numerous intuitive figures to make the content more accessible the book explores several potential solutions to this topic ensuring that readers are not only introduced to the latest advances in ILC for systems with random factors but also gain an in depth understanding of the intrinsic relationship between incomplete information environments and essential tracking performance It is a valuable resource for academics and engineers as well as graduate students who are interested in learning about control data driven control networked control systems and related fields

Real-time Iterative Learning Control Jian-Xin Xu,Sanjib K. Panda,Tong Heng Lee,2008-12-12 Real time Iterative Learning Control demonstrates how the latest advances in iterative learning control ILC can be applied to a number of plants widely encountered in practice The book gives a systematic introduction to real time ILC design and source of illustrative case studies for ILC problem solving the fundamental concepts schematics configurations and generic guidelines for ILC design and implementation are enhanced by a well selected group of representative simple and easy to learn example applications Key issues in ILC design and implementation in linear and nonlinear plants pervading mechatronics and batch processes are addressed in particular ILC design in the continuous and discrete time domains design in the frequency and time domains design with problem specific performance objectives including robustness and optimality design in a modular approach by integration with other control techniques and design by means of classical tools based on Bode plots and state space

Iterative Learning Control Algorithms and Experimental Benchmarking Eric Rogers,Bing Chu,Christopher Freeman,Paul Lewin,2023-01-12 Iterative Learning CONTROL ALGORITHMS AND EXPERIMENTAL BENCHMARKING Iterative Learning Control Algorithms and Experimental Benchmarking Presents key cutting edge research into the use of iterative learning control The book discusses the main methods of iterative learning control ILC and its interactions as well as comparator performance that is so crucial to the end user The book provides integrated coverage of the major approaches to date in terms of basic systems theoretic properties design algorithms and experimentally measured performance as well as the links

with repetitive control and other related areas Key features Provides comprehensive coverage of the main approaches to ILC and their relative advantages and disadvantages Presents the leading research in the field along with experimental benchmarking results Demonstrates how this approach can extend out from engineering to other areas and in particular new research into its use in healthcare systems rehabilitation robotics The book is essential reading for researchers and graduate students in iterative learning control repetitive control and more generally control systems theory and its applications

Linear and Nonlinear Iterative Learning Control Jian-Xin Xu,Ying Tan,2003-09-04 This monograph summarizes the recent achievements made in the field of iterative learning control The book is self contained in theoretical analysis and can be used as a reference or textbook for a graduate level course as well as for self study It opens a new avenue towards a new paradigm in deterministic learning control theory accompanied by detailed examples **Iterative Learning Control for Multi-agent Systems Coordination** Shiping Yang,Jian-Xin Xu,Xuefang Li,Dong Shen,2017-03-03 A timely guide using iterative learning control ILC as a solution for multi agent systems MAS challenges showcasing recent advances and industrially relevant applications Explores the synergy between the important topics of iterative learning control ILC and multi agent systems MAS Concisely summarizes recent advances and significant applications in ILC methods for power grids sensor networks and control processes Covers basic theory rigorous mathematics as well as engineering practice

Iterative Learning Control for Deterministic Systems Kevin L. Moore,2012-12-06 The material presented in this book addresses the analysis and design of learning control systems It begins with an introduction to the concept of learning control including a comprehensive literature review The text follows with a complete and unifying analysis of the learning control problem for linear LTI systems using a system theoretic approach which offers insight into the nature of the solution of the learning control problem Additionally several design methods are given for LTI learning control incorporating a technique based on parameter estimation and a one step learning control algorithm for finite horizon problems Further chapters focus upon learning control for deterministic nonlinear systems and a time varying learning controller is presented which can be applied to a class of nonlinear systems including the models of typical robotic manipulators The book concludes with the application of artificial neural networks to the learning control problem Three specificways to neural nets for this purpose are discussed including two methods which use backpropagation training and reinforcement learning The appendices in the book are particularly useful because they serve as a tutorial on artificial neural networks **Iterative Learning Control for Systems with Iteration-Varying Trial Lengths** Dong Shen,Xuefang Li,2019-01-29 This book presents a comprehensive and detailed study on iterative learning control ILC for systems with iteration varying trial lengths Instead of traditional ILC which requires systems to repeat on a fixed time interval this book focuses on a more practical case where the trial length might randomly vary from iteration to iteration The iteration varying trial lengths may be different from the desired trial length which can cause redundancy or dropouts of control information in ILC making ILC design a

challenging problem The book focuses on the synthesis and analysis of ILC for both linear and nonlinear systems with iteration varying trial lengths and proposes various novel techniques to deal with the precise tracking problem under non repeatable trial lengths such as moving window switching system and searching based moving average operator It not only discusses recent advances in ILC for systems with iteration varying trial lengths but also includes numerousintuitive figures to allow readers to develop an in depth understanding of the intrinsic relationship between the incomplete information environment and the essential tracking performance This book is intended for academic scholars and engineers who are interested in learning about control data driven control networked control systems and related fields It is also a useful resource for graduate students in the above field **Optimal Iterative Learning Control** Bing Chu,David H. Owens,2025-07-14 This book introduces an optimal iterative learning control ILC design framework from the end user s point of view Its central theme is the understanding of model dynamics the construction of a procedure for systematic input updating and their contribution to successful algorithm design The authors discuss the many applications of ILC in industrial systems applications such as robotics and mechanical testing The text covers a number of optimal ILC design methods including gradient based and norm optimal ILC Their convergence properties are described and detailed design guidelines including performance improvement mechanisms are presented Readers are given a clear picture of the nature of ILC and the benefits of the optimization based approach from the conceptual and mathematical foundations of the problem of algorithm construction to the impact of available parameters in making acceleration of algorithmic convergence possible Three case studies on robotic platforms an electro mechanical machine and robot assisted stroke rehabilitation are included to demonstrate the application of these methods in the real world With its emphasis on basic concepts detailed design guidelines and examples of benefits Optimal Iterative Learning Control will be of value to practising engineers and academic researchers alike Discrete-Time Adaptive Iterative Learning Control Ronghu Chi,Na Lin,Huimin Zhang,Ruikun Zhang,2022-03-21 This book belongs to the subject of control and systems theory The discrete time adaptive iterative learning control DAILC is discussed as a cutting edge of ILC and can address random initial states iteration varying targets and other non repetitive uncertainties in practical applications This book begins with the design and analysis of model based DAILC methods by referencing the tools used in the discrete time adaptive control theory To overcome the extreme difficulties in modeling a complex system the data driven DAILC methods are further discussed by building a linear parametric data mapping between two consecutive iterations Other significant improvements and extensions of the model based data driven DAILC are also studied to facilitate broader applications The readers can learn the recent progress on DAILC with consideration of various applications This book is intended for academic scholars engineers and graduate students who are interested in learning control adaptive control nonlinear systems and related fields *Iterative Learning Control* Kevin L. Moore,2000 Iterative Learning Control for Network Systems Under Constrained Information

Communication Wenjun Xiong,Zijian Luo,Daniel W. C. Ho,2024-03-26 This book focuses on the subject area of Network Systems and Control Theory providing a comprehensive examination of the dynamic behavior of networked systems operating under communication constraints It introduces innovative iterative learning control strategies that aim to ensure stability consistency and security of networked systems The field of networked systems has garnered significant interest from scientists and engineers across various disciplines including information electrical transportation life social and management sciences This book consistently addresses a wide range of issues related to networked systems emphasizing the critical impact of communication constraints on stability and security It highlights the effectiveness and importance of iterative learning methods in tackling these challenges Suitable for both undergraduate and graduate students interested in networked systems and iterative learning control this book alsoserves as a valuable resource for university faculty and engineers engaged in complex systems control theory research and real world applications Its broad appeal extends to professionals working in related fields seeking a deeper understanding of networked systems and their control mechanisms

Data-Driven Iterative Learning Control for Discrete-Time Systems Ronghu Chi,Yu Hui,Zhongsheng Hou,2022-11-15 This book belongs to the subject of control and systems theory It studies a novel data driven framework for the design and analysis of iterative learning control ILC for nonlinear discrete time systems A series of iterative dynamic linearization methods is discussed firstly to build a linear data mapping with respect of the system s output and input between two consecutive iterations On this basis this work presents a series of data driven ILC DDILC approaches with rigorous analysis After that this work also conducts significant extensions to the cases with incomplete data information specified point tracking higher order law system constraint nonrepetitive uncertainty and event triggered strategy to facilitate the real applications The readers can learn the recent progress on DDILC for complex systems in practical applications This book is intended for academic scholars engineers and graduate students who are interested in learning control adaptive control nonlinear systems and related fields *Iterative Learning Control over Random Fading Channels* Dong Shen,Xinghuo Yu,2023-12-22 Random fading communication is a type of attenuation damage of data over certain propagation media Establishing a systematic framework for the design and analysis of learning control schemes the book studies in depth the iterative learning control for stochastic systems with random fading communication The authors introduce both cases where the statistics of the random fading channels are known in advance and unknown They then extend the framework to other systems including multi agent systems point to point tracking systems and multi sensor systems More importantly a learning control scheme is established to solve the multi objective tracking problem with faded measurements which can help practical applications of learning control for high precision tracking of networked systems The book will be of interest to researchers and engineers interested in learning control data driven control and networked control systems **Practical Iterative Learning Control with Frequency Domain Design and Sampled Data**

Implementation Danwei Wang,Yongqiang Ye,Bin Zhang,2014-06-19 This book is on the iterative learning control ILC with focus on the design and implementation We approach the ILC design based on the frequency domain analysis and address the ILC implementation based on the sampled data methods This is the first book of ILC from frequency domain and sampled data methodologies The frequency domain design methods offer ILC users insights to the convergence performance which is of practical benefits This book presents a comprehensive framework with various methodologies to ensure the learnable bandwidth in the ILC system to be set with a balance between learning performance and learning stability The sampled data implementation ensures effective execution of ILC in practical dynamic systems The presented sampled data ILC methods also ensure the balance of performance and stability of learning process Furthermore the presented theories and methodologies are tested with an ILC controlled robotic system The experimental results show that the machines can work in much higher accuracy than a feedback control alone can offer With the proposed ILC algorithms it is possible that machines can work to their hardware design limits set by sensors and actuators The target audience for this book includes scientists engineers and practitioners involved in any systems with repetitive operations

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