

# Agilent 33120A

## Function / Arbitrary Waveform Generator

### Quick Reference Guide

#### Front-Panel Menu Reference

Use *Recall Menu* as a shortcut to recall the last command executed.



#### A: MODULATION MENU

1. AM SHAPE → 2. AM SOURCE → → → 9. FSK RATE → 10. FSK SRC

- |                |  |
|----------------|--|
| 1. AM SHAPE    | Selects the shape of the AM modulating waveform.                     |
| 2. AM SOURCE   | Enables or disables the internal AM modulating source.               |
| 3. FM SHAPE    | Selects the shape of the FM modulating waveform.                     |
| 4. BURST CNT   | Sets the number of cycles per burst (1 to 50,000 cycles).            |
| 5. BURST RATE  | Sets the burst rate in Hz for an internal burst source.              |
| 6. BURST PHASE | Sets the starting phase angle of a burst (-999 to +999 degrees).     |
| 7. BURST SRC   | Selects an internal or external gate source for burst modulation.    |
| 8. FSK FREQ    | Sets the FSK "tag" frequency.  |
| 9. FSK RATE    | Selects the internal FSK rate between the carrier and FSK frequency. |
| 10. FSK SRC    | Selects an internal or external source for the FSK rate.             |

#### B: SWEEP (Sweep) MENU

1. START F → 2. STOP F → 3. SWEEP TIME → 4. SWEEP MODE

- |               |   |
|---------------|---|
| 1. START F    | Sets the start frequency in Hz for sweeping.      |
| 2. STOP F     | Sets the stop frequency in Hz for sweeping.       |
| 3. SWEEP TIME | Sets the repetition rate in seconds for sweeping. |
| 4. SWEEP MODE | Selects linear or logarithmic sweeping.           |

#### C: EDIT MENU \*

1. NEW ARR → 2. POINTS → → → → 6. SAVE AS → 7. DELETE

- |               |   |
|---------------|---|
| 1. NEW ARR    | Initiates a new arr waveform or loads the selected arr waveform.        |
| 2. POINTS     | Sets the number of points in a new arr waveform (2 to 16,000 points).   |
| 3. LINE EDIT  | Performs a linear interpolation between two points in the arr waveform. |
| 4. POINT EDIT | Edits the individual points of the selected arr waveform.               |
| 5. INVERT     | Inverts the selected arr waveform by changing the sign of each point.   |
| 6. SAVE AS    | Saves the current arr waveform in non-volatile memory.                  |
| 7. DELETE     | Deletes the selected arr waveform from non-volatile memory.             |

\* The commands enclosed in square brackets [ ] are "hidden" until you make a selection from the NEW ARR command to initiate a new arr session.

#### D: SYSTEM MENU

1. OUT TERM → 2. POWER ON → → → → 5. COMMA → 6. REVISION

- |             |  |
|-------------|--|
| 1. OUT TERM | Selects the output termination (50Ω or high impedance).              |
| 2. POWER ON | Enables or disables power-up in power-down mode "0".                 |
| 3. ERROR    | Retrieves errors from the error queue (up to 25 errors).             |
| 4. TEST     | Performs a complete self-test.                                       |
| 5. COMMA    | Enables or disables a comma separator between digits on the display. |
| 6. REVISION | Displays the function generator's firmware revision codes.           |

#### E: Input / Output MENU

1. HWB ADDR → 2. INTERFACE → 3. BAUD RATE → 4. PARITY → 5. LANGUAGE

- |              |   |
|--------------|---|
| 1. HWB ADDR  | Sets the GPIB bus address (2 to 30).                  |
| 2. INTERFACE | Selects the GPIB or RS-232 interface.                 |
| 3. BAUD RATE | Selects the baud rate for RS-232 operation.           |
| 4. PARITY    | Selects even, odd, or no parity for RS-232 operation. |
| 5. LANGUAGE  | Verifies the interface language (GPIB).               |

#### F: CALIBRATION MENU \*

1. SECURED → 1. UNSECURED → 2. CALIBRATE → 3. CAL COUNT → 4. MESSAGE

- |              |  |
|--------------|--|
| 1. SECURED   | The function generator is secured against calibration; enter code to unsecure. |
| 1. UNSECURED | The function generator is unsecured for calibration; enter code to secure.     |
| 2. CALIBRATE | Performs individual calibrations; must be UNSECURED.                           |
| 3. CAL COUNT | Reads the total number of times the function generator has been calibrated.    |
| 4. MESSAGE   | Reads the calibration string (up to 31 characters) entered from remote.        |

\* The commands enclosed in square brackets [ ] are "hidden" unless the function generator is UNSECURED for calibration.



# Agilent 33120a Reference Guide

**G Thomas**



## **Agilent 33120a Reference Guide:**

Design of the Filtering and Sensing Part of the SmartSpectra Camera Joan Vila Francés, 2005-05-20 This document shows the current state of the research work done around the SmartSpectra project The SmartSpectra project is a Research Technological development and Demonstration RTD project funded under EU s Fifth Framework Programme FP5 by the Information Society Technologies IST Programme The project pursues the development of a Smart Multispectral System for Commercial Applications SmartSpectra is an acronym of Smart Multispectral System for Commercial Applications In this project a Smart Multispectral System will be designed and implemented The system will allow multispectral imaging with an affordable cost and proven robustness in order to achieve a broad use of multispectral techniques in several commercial areas and applications The system will have the capability to be integrated in currently established production systems Moreover it will be flexible enough to be applicable to a wide range of applications The document is organized as follows In the introductory chapter we present the SmartSpectra project emphasizing the parts in which we are involved Next chapter is devoted to explain the concept of the SmartSpectra camera defining its specifications Chapters 3 and 4 detail the realised work regarding Workpackages 2 and 3 of the project Workpackage 2 deals with the optical and sensing part of the SmartSpectra system It summarizes the state of the art in VIS NIR technologies lists the purchased sensors for the project and describes the AOTF Acousto Optic Tunable Filter technology Workpackage 3 explains the sensor electronics and interface Two different prototypes of the SmartSpectra camera are described along with the Firewire subsystem These chapters are followed by a Progress Review and Future Work Last chapter is a final summary of the work The document ends with a group of annexes showing the outcomes of the work

**Applied Analog Electronics: A First Course In Electronics** Kevin Karplus, 2023-06-06 This textbook is for a first course on electronics It assumes no prior electronics experience but does assume that students have had calculus 1 single variable differential calculus and high school physics A key idea of the course is that students need a lot of design experience and hands on work rather than a lot of theory The course is centered around the labs which are a mix of design labs and measurement modeling labs This unique volume takes students from knowing no electronics to being able to design and build amplifier and filter circuits for connecting sensors to microcontrollers within 20 weeks Students design a digital thermometer a blood pressure meter an optical pulse monitor an EKG an audio preamplifier and a class D power amplifier They also learn how to measure and characterize components including impedance spectroscopy of a loudspeaker and of electrochemical electrodes Related Link s *Signal* ,2003

*Electronic Test Instruments* Robert A. Witte, 2002 Electronic Test Instruments Analog and Digital Measurements Second Edition offers a thorough unified up to date survey of electronics instrumentation digital and analog Start with basic measurement theory then master all mainstream forms of electronic test equipment through real world application examples This new edition is now fully updated for the latest technologies with extensive new coverage of digital oscilloscopes power

supplies and more Instrument Control Toolbox 2, 2007 **IGISOL** Juha Äystö, Tommi Eronen, Ari Jokinen, Anu Kankainen, Iain Moore, Heikki Penttilä, 2014-01-23 The IGISOL group at the University of Jyväskylä studies the properties of nuclei far off the line of beta stability These studies are performed locally at the Jyväskylä Ion Guide Isotope Separator On Line IGISOL facility as well as at a number of other laboratories such as the ISOLDE facility in CERN at GANIL and in Helmholtzzentrum GSI the location of the future radioactive beam facility FAIR The group is also actively involved in work to support the development of international future facilities EURISOL and aforementioned FAIR This book presents carefully selected papers to portrait the work at IGISOL Previously published in the journals Hyperfine Interactions and European Physical Journal A Intelligent Unmanned Systems: Theory and Applications Agus Budiyo, Bambang Riyanto, Endra Joelianto, 2009-03-03 The book largely represents the extended version of select papers from the International Conference on Intelligent Unmanned System ICIUS 2007 which was jointly organized by the Center for Unmanned System Studies at Institut Teknologi Bandung Artificial Muscle Research Center at Konkuk University and Institute of Bio inspired Structure and Surface Engineering Nanjing University of Aeronautics and Astronautics The joint event was the 3rd conference extending from International Conference on Emerging System Technology ICESST in 2005 and International Conference on Technology Fusion ICTF in 2006 both conducted in Seoul ICIUS 2007 was focused on both theory and application primarily covering the topics on robotics autonomous vehicles and intelligent unmanned technologies The conference was arranged into three parallel symposia with the following scope of topics Unmanned Systems Micro air vehicle Underwater vehicle Micro satellite manned aerial vehicle Multi agent systems Autonomous ground vehicle Blimp Swarm intelligence learning and control Robotics and Biomimetics Artificial muscle actuators Smart sensors Design and applications of MEMS NEMS system Intelligent robot system Evolutionary algorithm Control of biological systems AI and expert systems Biological learning control systems Neural networks Genetic algorithm Control and Intelligent System Distributed intelligence Distributed decentralized intelligent control Distributed or decentralized control methods Distributed and bedded systems Embedded intelligent control Complex systems Discrete event systems Hybrid systems Networked control systems Delay systems Fuzzy systems Identification and estimation Nonlinear systems Precision motion control Control applications Control engineering education *Linear and Nonlinear Impedance Spectroscopy for the Study of Electrode/solution Interfaces* John Richard Peck, 2004 **Optics Letters**, 2002 *Electronics World*, 2008 *Integrated Hollow Core Waveguide Devices for Optical Sensing Applications* Dongliang Yin, 2006 9th International Symposium on Therapeutic Ultrasound Kullervo Hynynen, Jacques Souquet, 2010-03-23 Conference Location and Date Aix en Provence France 24-26 September 2009 **Optomechatronic Micro/nano Components, Devices, and Systems** Yoshitada Katagiri, 2004 Proceedings of SPIE present the original research papers presented at SPIE conferences and other high quality conferences in the broad ranging fields of optics and photonics These books provide prompt access to the latest innovations in research and technology in their respective fields

Proceedings of SPIE are among the most cited references in patent literature      **PDMS-on-silicon Microsystems** Yi-Chung  
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UNIRAS (FIRM),1992      *Technical Reference Guide for FAST Version 18* ,1989      Mechanical APDL Commands Quick  
Reference Guide ,2011      *GGSPRO Technical Reference Guide* Yates,Willmott,Brubaler,2012-01-01

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