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A Novel Lidar Ceilometer

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develop it The primary design considerations of optical signal to noise ratio range dependent overlap of the transmitter and receiver channels and manufacturability were balanced to develop an instrument with good signal to noise ratio fast turn on of overlap for detection of close range returns and a minimised number of optical components and simplicity of assembly for cost control purposes Second a novel imaging method for characterisation of transmitter receiver overlap as a function of range is described and applied to the instrument The method is validated by an alternative experimental method and a geometric calculation that is specific to the unique geometry of the instrument These techniques allow the calibration of close range detection sensitivity in order to acquire information prior to full overlap Finally signal processing methods used to automate the detection process are described A novel two part cloud base detection algorithm has been developed which combines extinction derived visibility thresholds in the inverted cloud return signal with feature detection on the raw signal In addition standard approaches for determination of visibility based on an iterative far boundary inversion method and calibration of attenuated backscatter profile using returns from a fully attenuating water cloud have been applied to the prototype The prototype design characterisation and signal processing have been shown to be appropriate for implementation into a commercial instrument The work that has been carried out provides a platform upon which a wide range of further work can be built

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